

# TUT 3

Uniqueness thm:

$$\textcircled{1} \begin{cases} y'' + p(t)y' + q(t)y = g(t) \\ y(t_0) = y_0 \\ y'(t_0) = y_0' \end{cases}$$

where  $p, q, g$  are cts on an open interval that contains the point  $t_0$ ,

Then  $\exists!$   $y = \phi(t)$  satisfies  $\textcircled{1}$  throughout  $I$ .

Consider  $L(y) = y'' + py' + qy = 0$

Def: Suppose  $y_1, y_2$  are the solution to  $L(y) = 0$ , then  $w(y_1, y_2)(t) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$

is called the Wronskian of  $y_1$  and  $y_2$

Actually, we want to make use of Wronskian to see if our solutions  $y_1, y_2$  to  $L(y) = 0$  are "different".

Thm: If  $y_1, y_2$  are 2 solutions of  $L(y)=0$ ,  
and  $\exists t_0$  s.t.  $W(y_1, y_2)(t_0) \neq 0$ , then

$y = c_1 y_1 + c_2 y_2$  includes all the solutions of  
 $L(y)=0$  for arbitrary  $c_1, c_2$ .

Abel thm: If  $y_1, y_2$  are the solution to  
 $L(y)=0$ , where  $p, q$  are cts, then Wronkian,  
 $W(y_1, y_2)(t) = C e^{-\int p}$ .

Remark: Abel thm implies the Wronkian of  
the solution of an ODE must be always zero  
or never zero. ( $C=0$  or  $C \neq 0$ ).

Thm: Let  $y_1, y_2$  be the solutions of  $L(y)=0$ ,  
where  $p, q$  are cts,

$y_1, y_2$  are linearly independent iff  $W \neq 0$ .

Remark: It is not true if  $y_1, y_2$  are not the  
solution of a ODE.

Nonhomogeneous equation:

$$L(y) = y'' + p(t)y' + q(t)y = g(t). \quad - \textcircled{2}$$

There is no a formula to solve this general nonhomogeneous equation.

We deal with the case of constant  $p, q$ .

To solve  $y'' + ay' + by = g(t)$

Step ①: find the general solution to the homogeneous equation  $y'' + ay' + by = 0$ ,

It is called complementary solution

$$y_c(t) = C_1 y_1 + C_2 y_2.$$

Step ②: to deal with  $g(t)$ ,

Method A: Method of Undetermined Coefficient

This method can only deal with  $g(t)$  of the following form:

$g(t)$ 

$$a_n x^n + a_{n-1} x^{n-1} + \dots + a_0$$

$$a e^{bx}$$

$$a_1 \sin b_1 x + a_2 \cos b_2 x$$

 $Y(x)$ 

$$D_n x^n + D_{n-1} x^{n-1} + \dots + D_0$$

$$D e^{bx}$$

$$D_1 \sin b_1 x + D_2 \cos b_2 x$$

We assume  $Y(t)$  to be the form corresponding to different form of  $g(t)$ , then sub in  $L(Y(t)) = g(t)$ , comparing both sides, we can find out the constants  $D_i$ .

Method (B): variation of Parameters

We can use this method to deal with all forms of  $g(t)$  (cls to have a unique solution),

Thm Suppose  $p, q, g$  are cls in  $\mathbb{R}$ , and  $y_1, y_2$  be found in step (1) (must be linearly independent), then

$$Y(t) = -y_1 \int_{t_0}^t \frac{y_2(s)g(s)}{w(s)} ds + y_2 \int_{t_0}^t \frac{y_1(s)g(s)}{w(s)} ds$$

Step ③: the solution to  $L(y) = g(t)$

$$\text{is } y = c_1 y_1 + c_2 y_2 + Y(t).$$

Question:

①: Consider  $y_1(t) = \begin{cases} t^2 & t \leq 0 \\ 0 & t > 0 \end{cases}$ ,  $y_2(t) = \begin{cases} 0 & t \leq 0 \\ t^2 & t > 0 \end{cases}$

Show that

a  $w(y_1, y_2)(t) = 0$

b  $\{y_1, y_2\}$  are linearly independent on  $(-\infty, \infty)$

c Can  $y_1, y_2$  be 2 solutions of a 2nd linear ODE.

Ans: (a)

$$w = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = \begin{cases} \begin{vmatrix} t^2 & 0 \\ 2t & 0 \end{vmatrix} = 0 & t \leq 0 \\ \begin{vmatrix} 0 & t^2 \\ 0 & 2t \end{vmatrix} = 0 & t > 0 \end{cases}$$

(b)  $k_1 y_1 + k_2 y_2 = 0$ ,

If  $t \leq 0$ ,  $k_1 t^2 = 0 \Rightarrow k_1 = 0$

Similarly, if  $t > 0$ , then  $k_2 = 0$ ,  
they are linearly independent!!

$C$  So suppose they are the  
 solution of a 2nd linear ODE, then by  
 thm,  $y_1, y_2$  are linearly independent iff  
 $W \neq 0$ , But by a, b, there is a contradiction!!  
 furthermore,  $y_1, y_2 \in C^1$ , they are not 2-  
 differentiable.

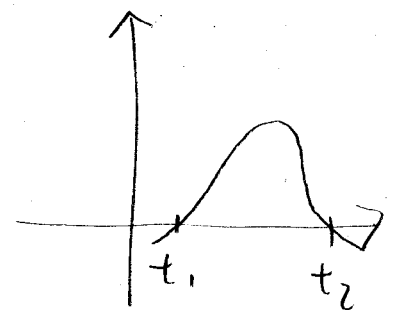
(2) If  $y_1, y_2$  are linearly independent  
 solution of  $y'' + p(t)y' + q(t)y = 0$ ,  
 show that between consecutive zeros of  $y_1, \exists!$   
 zero of  $y_2$ .

Ans: Assume 2 consecutive zeros of  $y_1$  are  
 $t_1, t_2$ , i.e.  $y_1(t_1) = y_1(t_2) = 0$ .  $t_1 < t_2$ .

then, by cts of  $y_1$ ,  $y_1 < 0$  or  $y_1 > 0$  in  
 $(t_1, t_2)$ .

Suppose  $y_1(t) > 0 \forall t \in (t_1, t_2)$ .

So  $y_1'(t_1) > 0$  and  $y_1'(t_2) < 0$



$W(y_1, y_2) = y_2' y_1 - y_1' y_2 \neq 0 \quad \forall t \in \mathbb{R}$  as  $y_1, y_2$  are linearly independent.

So  $W = Ce^{-\int P}$   $> 0$  or  $< 0 \quad \forall t \in \mathbb{R}$

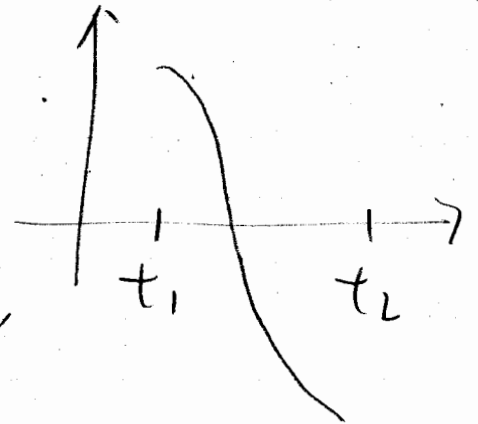
If  $W > 0$ ,

$$W(t_1) = -y_1'(t_1)y_2(t_1) > 0$$

$$W(t_2) = -y_1'(t_2)y_2(t_2) > 0$$

So  $y_2(t_1) > 0$  and  $y_2(t_2) < 0$ ,

$\exists$  zero of  $y_2$



Other cases are left to you.

If  $\exists$  2 zeros of  $y_2$  between  $t_1, t_2$ .

say  $t_1 < t_3 < t_4 < t_2$ , By above argument, interchange  $y_1, y_2$ ,  $\exists$  a zero of  $y_1$  between  $t_1, t_3$  contradicts with our assumption.

③ Reduction of order:

find the solution of  $t^2 y'' - 4t y' + 6y = 0, t > 0$

given that  $y_1(t) = t^2$  is a solution.

$$\text{let } y_2 = t^2 v, \quad y_2' = 2tv + t^2 v', \quad y_2'' = 2v + 2tv' + 2tv' + t^2 v''$$

$$(2v + 4tv' + t^2 v'')t^2 - 4t(2tv + t^2 v') + 6t^2 v = 0$$

$$t^4 v'' = 0$$

$$v = C_1 t + C_2$$

$$\therefore y_2 = vt^2$$

$$= t^2(C_1 t + C_2) = C_1 t^3 + C_2 t^2$$

So  $y = C_1 t^3 + C_2 t^2$  is the solution.

④ Solve  $y'' + 2y' + 5y = 3\sin 2t$

Ans:  $r^2 + 2r + 5 = 0$ ,

$$y_c(t) = e^{-t}(C_1 \cos 2t + C_2 \sin 2t)$$

$$\text{let } Y(t) = A \sin 2t + B \cos 2t$$

$$Y'(t) = 2A \cos 2t - 2B \sin 2t$$

$$Y''(t) = -4A \sin 2t - 4B \cos 2t$$

$$(A + 4B) \cos 2t + (-4A + B) \sin 2t = 3 \sin 2t$$

$$A = \frac{3}{17}, \quad B = -\frac{12}{17}$$



$$\hookrightarrow y = e^{-t}(C_1 \cos 2t + C_2 \sin 2t) + \frac{3}{17} \sin 2t - \frac{12}{17} \cos 2t$$

⑤ Solve  $y'' + y = 2 \tan t$   $0 < t < \frac{\pi}{2}$

Ans:  $r^2 + 1 = 0$

$\hookrightarrow y_c(t) = C_1 \cos t + C_2 \sin t$

$$W = \begin{vmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{vmatrix} = 1$$

$$Y(t) = -\cos t \int \frac{\sin t (2 \tan t)}{1} + \sin t \int \frac{\cos t (2 \tan t)}{1}$$

$$= -2 \cos t \int \sec t - \cos t - 2 \sin t \cos t$$

$$= -2 \cos t \int \sec t$$

$$= -2 \cos t \ln(\sec t + \tan t)$$

$$\therefore y = C_1 \cos t + C_2 \sin t - 2 \cos t \ln(\sec t + \tan t)$$